TRANSLATION (BM-154PCT-original):

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CLOSING DEVICE FOR DOORS, HOODS, HATCHES OR THE LIKE, ESPECIALLY OF VEHICLES SUCH AS MOTOR VEHICLES

The invention pertains to a closing device of the type indicated in the introductory clause of Claim 1. A closing device of this type is used primarily on the rear hatches of vehicles. The grip housing is mounted in an opening made in the outer panel of the hatch. The grip flap and also the grip housing itself are advisably covered by a rubber skin, through which the grip flap can be actuated manually.

In the known closing device of this type (WO 98/01643, Figures 15-18), a projecting pin is provided a certain distance away from the pivot axis of the grip flap; this pin projects from an opening in the sidewall of the grip housing. On the outside surface of the sidewall of the housing, there is an electric switch with a contact actuator, upon which the projecting pin acts when the grip flap is actuated. Outside the grip housing, the cable leading to the electric switch is provided with clips, which serve to relieve the strain on the cable connected to the switch. To provide the restoring force for the grip flap, a ball is used, which is installed in a side

opening in the grip flap and is spring-loaded by a compression spring. Inside the grip housing, the spring-loaded ball works together with a slanted surface, which slants toward the starting position of the grip flap. When the grip flap is manually actuated, the ball rolls down along the slanted surface and compresses the compression spring. One of the components of the force exerted by the compression spring provides a restoring force, which acts in the direction toward the starting position of the grip flap. When the grip flap was actuated, the ball rolled down the slanted surface. This known closing device is bulky and has many individual parts. These numerous parts complicate the assembly work and lead to relatively high production costs.

It is known (DE 100 20 172 A1) that a grip can be mounted in front of the contact actuator of an electric switch and can exert a restoring force on a membrane by means of disk springs or leaf springs. The membrane closes an opening in the grip housing and offers an actuating surface for the human hand.

In the case of an electronic key (DE 199 15 969 A1), it is known that electric switches can be mounted in the key housing, and that the switches can be provided with plungers to serve as contact actuators. A housing wall consists of a plastic membrane, under which a plate-shaped support element is

provided. This support element has drivers, which are aligned with the plungers of the electric switches and are seated in openings in the support element by way of torsion springs. These torsion springs exert a restoring force on the drivers to keep the plastic membrane pressed down into its starting position, in which the plungers of the switches are unactuated. When a human hand presses down on the membrane, the drivers of the support element actuate the plungers of the electric switches, for which purpose the restoring force acting on the drivers must be overcome.

The invention is based on the task of developing a low-cost closing device of the type indicated in the introductory clause of Claim 1 which consists of only a few parts and which occupies a minimum of space. This is accomplished according to the invention by the measures cited in Claim 1, to which the following special meaning attaches.

The spring-loading of the switch can simultaneously take over the job of providing the restoring force for the entire closing device, i.e., the force which tries to hold the grip flap in its rest position. As a result, there is no need for any actuating means or switches outside the grip housing. It is recommended that the switch be installed underneath the grip flap. The switch itself is integrated into the grip housing,

which is advisably designed as a shell. This housing shell is covered by the grip flap.

Additional embodiments of the invention can be derived from the subclaims. Several exemplary embodiments of the invention are illustrated in the drawings:

-- Figure 1 shows a cross section through the inventive closing device before it is installed in the rear hatch of a vehicle, while the grip flap is in its rest position;

-- Figure 2 shows the same closing device as that of Figure 1, but with the grip flap in its working position;

-- Figure 3 shows a part of the grip housing of a closing device similar to that of Figures 1 and 2, namely, from the perspective of the rear of the housing, in the viewing direction of arrow III in Figure 1;

-- Figure 4 shows a perspective view looking down onto the front side of the housing of the closing device shown in Figure 3, after the electric switch in its mounting shell has been installed;

-- Figure 5 is a view of the closing device similar to that of Figure 3, showing the relationships which are present after the electric switch and the mounting shell have been installed in the grip housing; and

-- Figure 6 shows an alternative design of the closing

device similar to Figure 2 on an enlarged scale.

The closing device shown in Figures 1 and 2 comprises a grip housing 10 with a grip flap 12, supported pivotably on the housing at 11. The grip housing 10 consists of a shell, which is open toward the bottom surface 13 of the grip flap 12. A mounting shell 30 is attached to the floor 14 of the housing shell to facilitate the installation of the switch 20; this mounting shell is also open toward the bottom surface 13 of the grip flap. These relationships are especially clear in Figures 3-5.

The grip housing 10 has an opening 15, through which an electric cable 40 can be passed, the two wires 41, 42 of which continue along the mounting shell 30 until they reach the electric switch, where they are connected to two stationary contacts 21, 22. Inside the mounting shell 30 there is also a strain-relief device 31, 32 for the electric cable 40. This device consists here of two pins 31, 32 seated in the interior 33 of the shell, around which the two cable wires 41, 42 are bent in labyrinthine fashion, namely, in the form of an "S". After the switch 20 and the cable have been installed, the interior 33 of the mounting shell 30 is filled with a casting compound (not shown). This compound at least partially covers the switch housing 23 and the two cable wires 41, 42 and ensures

that the switch housing 23 remains permanently in place in the mounting shell 30. This group of parts forms a structural unit 44, which can be preassembled, consisting of the mounting shell 30, the switch 20 mounted in it, and the cable 40, seated in the strain-relief device 31, 32.

After it has been assembled, this structural unit 44 is introduced through the previously mentioned opening 15 in the grip housing 10. The opening, as Figure 3 shows, is provided with a suitable profile. The profile of the opening has a step-like form so that, during the insertion motion illustrated by an installation arrow 34 in Figure 1, the contact actuator 24 projecting from the unit can pass unhindered into the interior of the grip housing 10. Snap fasteners (not shown) ensure that the mounting shell 30 is held in a defined position in the grip housing 10. The mounting shell 30 has a tab 35 at one end with an outline which is complementary to the stepped shape of the opening 15; after installation, this tab essentially covers the opening 15. At first, only the grip flap 12, pivotably supported at 11, is seated in the grip housing 10.

Figure 1 shows the installation position of the grip housing 10 in an opening 16 cut in the outside panel 17 of the rear hatch of a vehicle, the housing containing the previously mentioned structural unit 44. The opening of the shell-like

grip housing 10 is covered by an elastomeric skin 36, which has a 3-dimensional profile; the central section of the skin rests against the outside surface 18 of the grip flap 12. The elastomeric skin and the grip housing 10 together form a capsule for the installed structural unit and for the grip flap 12. The edges of the skin 36 extend around the bent-over edges of the grip housing 10 and thus act as seals after the closing device has been attached to the outside panel 17 by screws 39.

Figure 2 shows the details of the design of the electric switch 20 and illustrates its special function. The switch housing 24 comprises a relatively stiff bottom part 25 and an elastomeric upper part 26, on which the contact actuator 24 in the form of a plunger is formed. In the interior of the switch housing 23, between the two parts 25, 26, there is a curved diaphragm spring 27. When this spring is in the starting position, its curved part holds the contact actuator 24 in a defined starting position, which is illustrated in Figure 1 by an auxiliary line labeled 24.1. The diaphragm spring 27 exerts an elastic load on the contact actuator 24 as illustrated by the force arrow 28 in Figure 1. The front end of the plunger-like contact actuator 24 touches a projection 19 provided on the bottom surface 13 of the grip flap 12; it is possible for a positive engagement to be produced here.

The diaphragm spring 27 consists of electrically conductive material. In the starting position 24.1 of Figure 1, the diaphragm spring 27 is a certain distance away from the two stationary contacts 21, 22. In this first contact position, which is the position normally present, the two electrical contacts 21, 22 are not connected to each other; the switch 20 is in its "off" position. The spring-loading 28 of the contact actuator 24 serves in the present case to hold the grip flap in the rest position in the grip housing 10 shown in Figure 1, as illustrated in Figure 1 by the auxiliary line 12.1. The spring-loading 28 of the diaphragm spring 27 provides a restoring action on the grip flap 12 in the direction toward this rest position 12.1. This restoring force is illustrated by a force arrow 38 in Figure 1.

In the original state, the grip housing 10 is provided only with the grip flap 12 mounted inside; if desired, the elastomeric skin 36 can also be inserted at this point. In this partially assembled state, the grip flap 12 is not yet spring-loaded by a restoring force. This restoring force is not produced until the structural unit 44 is installed. This is inserted into the previously mentioned assembly in the direction of the previously mentioned installation arrow 34 and then fixed in place there by means of latching devices (not shown). Then

the contact actuator 24 comes to rest against the projection 19 on the grip flap 12 and provides the previously mentioned restoring force 38.

As previously mentioned, the grip flap 12 is normally in its rest position 12.1 shown in Figure 1. The flap remains in this position until a human hand 29 actuates the elastomeric skin 36.

This situation changes when a hand 29, as Figure 2 shows, exerts pressure on the grip flap 12 and therefore pivots it in the direction of the pivot arrow 37 around the pivot axis 11. Then the plunger-like contact actuator 24 is pressed inward and arrives in its actuating position, indicated by the auxiliary line 24.2 in Figure 2. In this actuating position 24.2, the diaphragm spring 27, which rests against the inside end of the contact actuator 24, flattens out until electrical contact is established between the two stationary contact parts 21, 22. The switch 20 is thus now in its "on" state, as a result of which the desired functions in the associated closing device can proceed. The position of the grip flap illustrated by the auxiliary line 12.2 in Figure 2 proves to be the effective working position of the grip flap 12. The previously mentioned actuation 37 in the direction toward the working position 12.2 must proceed in opposition to the restoring force 38. When the

human hand 29 releases the grip flap 12, the flap will move back into its rest position 12.1 of Figure 1 as a result of the spring-loading 28 acting on it from the side where the spring is located. During the previously mentioned actuation 37 of the grip flap, the diaphragm spring 27 is put under even greater tension and thus produces an even greater elastic force 28 than that present in Figure 1.

In some cases it would also be possible to install the switch on the outside surface of the grip housing 10 and to introduce the plunger-like contact actuator 24 into the interior of the housing through an appropriate opening. The grip flap 12 would be supported in the same way as that shown in Figure 1.

In the present exemplary embodiment, the mounting shell 30 is provided with an elevation 43, which serves as a stop for the grip flap 12 during the actuation process. The design of the elevation 43 can be seen very clearly in Figure 4. As a result of the stop action of the elevation 43, an overstroke is prevented, and damage to the components which could be caused by excessive actuating force is avoided. The elevation 43 could also be component of the housing 10 in certain cases.

If it is desired to increase the restoring force 38 acting on the grip flap 12, this can be easily realized by stacking several diaphragm springs 27 on top of each other in the

interior of the switch 20. As a result, the restoring force 38 can be easily doubled or tripled. In place of a diaphragm spring 27, it would also be possible for the spring-loading 28 of the contact actuator 24 to be provided by other types of springs known in and of themselves, such as compression springs.

When the electric switch 20 is actuated, it may be subjected only to a certain maximum actuating force, which is designated by the number 45 in Figure 6. In the rest position of the grip flap, shown in Figure 1, there is a gap 46 between the grip flap 12 and the grip housing 10; this gap is larger than the distance which the diaphragm spring 27 travels between the two contact positions 24.1 and 24.2 in Figures 1 and 2. For design reasons, however, there is a certain amount of play between the components, and in certain cases this play can have the effect of changing the size of the previously mentioned gap 46. Thus the system must be capable of tolerating a certain amount of overstroke.

In order to protect the electric switch 20 from excessive actuating force 45 in the latter case as well, it is proposed that an elastic element 48 be installed between the contact actuator 24 and the grip flap 12. This elastic element 48 is intended to transmit the actuating force 45 illustrated in Figure 6 to the electrical switch 20. The elastic element 48

can be deformed when the actuating force 45 it is transmitting exceeds a certain value. This deformation continues until, during the movement 37 also indicated in Figure 6, the grip flap 12 comes to rest against the grip housing 10 or against the mounting shell 30 seated therein, as shown at 47 in Figure 6. In the present case, the elastic element 48 is formed by the contact actuator 24 of the electric switch 20 itself.

This contact actuator 24 is designed here as a plunger and consists of elastomeric material. It has been assumed in Figure 6 that the actuating force 45 is strong enough to have deformed the plunger material to the extent illustrated by the deformation arrows 49. The cylindrical plunger thus assumes a convex shape. This has the effect of protecting the switch 20.

Figure 6 shows the simplest way in which an elastic element can be provided in this area. Another possibility consists in installing, for example, a separate spring element between the bottom 13 of the grip flap 12 shown in Figure 1 and the contact actuator 24 of the switch 20.

List of Reference Numbers

10	grip housing
11	pivot axis
12	grip flap
12.1	rest position of 12
12.2	working position of 12
13	bottom of 12
14	shell bottom of 10
15	opening in 10
16	cutout in 17
17	outer panel
18	outside surface of 12
19	projection on 13 for 24
20	electric switch
21	first contact of 20
22	second contact of 20
23	switch housing of 20
24	contact actuator of 20
24.1	starting position of 24
24.2	actuating position of 24
25	bottom part of 23
26	elastomeric upper part of 23

27 diaphragm spring of 20

28 force arrow of the spring-loading of 24

29 human hand

30 mounting aid, mounting shell

31 strain-relief device of 40, first pin

32 strain-relief device of 40, second pin

33 shell interior of 30

34 mounting arrow of 44 in 10

35 terminal tab of 30

36 elastomeric skin on 10

37 pivot-motion arrow of 12

38 arrow of the restoring force of 12

39 screw for 10 (Figure 1)

40 electric cable

41 conductor of 40, first wire of 40

42 conductor of 40, second wire of 40

43 elevation, stop on 30

44 structural unit

45 actuating force for 12 or 20 (Figure 6)

46 gap between 12 and 10 (Figure 1)

47 contact between 13 and 30 (Figure 6)

48 elastic element, elastomeric plunger (Figure 6)

49 deformation arrows of 48 or 24 under 45 (Figure 6)